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SAFE AND SECURED INCORPORATION OF MULTI-SENSOR INTELLIGENT TRACTION SYSTEM

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ABSTRACT

A new kind of approaches is exhibited to ensure the railway safety and thereby assuring a secured travel. This project mainly performs the detection of faults that occurs due to cracks on tracks, obstacle and explosives. For better and safe travel, the cracks on rails are periodically checked, for this, left and right alignment are said to be performed using IR sensors and added Ultra Sonic crack detection can also be performed for effective and better results. Metal(proximity)sensor and obstacle sensor check is carried out in order to avoid the running train either get collided or hit by an obstacle. Communication between the driver and control room can be done using radio-based operation. Promisingly, a safe and secured travel can be assured for the passengers using this transportation system.

Keywords –Wireless technology, Ultra-Sonic crack detection, sensors, buzzer system.

INTRODUCTION

Railway transportation system is one among the commonly used economical transportation system in India. Almost nearly 24 million passengers use the railway system on a daily basis. Railway authorities had made an analysis of the recent accidents and customer complaints to provide a safe and secured system which can be widely used throughout the railway connecting system. The major reason which is being analysed for the cause of the railway accidents is the Signalling System which is being done manually either by a telephonic intercom call or by a walkie talky, were the signal information is being sent from a station to the next upcoming station, and with this receiving information signal for the trains are said to be operated throughout the network. In Jammu & Kashmir, due to extreme cold weather conditions, the Loco-Pilots find it difficult to have an accurate view of the Signal. Hence, a complete networking system can be implemented, were an automatic signalling can be done. The trains can be controlled which would provide a better traffic control system as well as the monitoring can be done.

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With the increased usage of railway system, the transportation system continue to upgrade at a remarkable note to maintain the efficiency, reliability, safety and security. The lack of safety and security is caused mainly due to fact that a periodic/random fault identification is not properly done. Recent advances concentrates in vehicle health monitoring system, [7] E-BMA(Bit Map Assisted) protocol concentrates on developing better energy efficiency and to monitor the dynamic behaviour of railway wagons. Indian railways have planned for a trail check for the avoidance of the above discussed factors in the DEMU(figure 1) train which is a recent technology train being introduced in the Sub-Urban & Rural places across India were the people density is less. DEMU(Diesel Electric Multiple Units) is a self-propelled train consisting of Driving Power Car and Trailer Cars which would run at a speed of 110 km/h.



Fig 1. A view of a DEMU Train in J&K

General schematic diagram(Figure 2) illustrating the three railway layers: traffic management, control and safety layers. Traffic Management layer is concerned with the indirect control of signalling, it is an important layer when compared to the other two layers because it does the complete operation. So this layer is also known as operational layer. This layer takes care of creating time table, customer's information and rail information system. This layer is not responsible for safety but it is given higher priority for its operations.



Fig 2. Schematic diagram of railway layers

Safety signalling layer provides safety protection through the use of signals, train based protection like detecting explosives and collision avoidance, protection for passengers and train's infrastructure such as fire extinguisher. Control layer is a direct control signal which does the work of setting routes, track the location of trains, automatic train operation which makes the train to halt when it detects a red signal, automatic system waits and responds only when there is no action from driver's side.

By the use of the above layers an periodic verification will be carried out and routes are correctly monitored from the rail control. Train management system performs complete operation, this intern reduces cost and added information's would be available to the passenger's, driver's cabin, and control room. Layer helps to provide consistent message to the concerned authority, by which a safety travel is assured.

Railway transportation system are mainly used to protect and manage the trains over the infrastructure, including the signalling systems and to manage train collision, a topology-based operation are performed for modelling railway networks that can be used for train control system,[8]. Track gauge, super-elevation and track axis coordinates are railway parameters that are measured using a surveying system [10]LVDT(Linear Variable Differential Transformers). And the importance of train detection in railway signalling, control systems and its highlights are discussed [3]. A new approach to railway traffic analysis is to reconstruct the speed profile and its energy consumption [6]. The analytical model and simulation of the traction system are developed and its results are simulated using Proteus, MPLABs.

II. BASIC COMPONENTS AND PRINCIPLES OF THE SYSTEM

Basic principle of the system is to communicate the information about weather, obstacle or any other emergency details between the train and control room. The medium of communication is done using RFID. The general block diagram is shown in figure 3.



Fig 3. General block diagram of the project

A. Block Signaling

In this section, automatic signaling concept is defined. Signals are placed to indicate the approaching train's action and depending on the signaling system, the operational speed of the train will be changed.

Figure 4. shows the two-aspect signaling systems, train can move only when there is a green signal and halts when it is red and added the braking distance from line speed is distributed across the block sections. Blocks are said to be the railway lines that are divided into sections. By using the PIC16F877A controller the signals are automated and transmitted through RF transmitter.



Fig 4. Block diagram for train signal

B. Basic Design

Basic design includes five parts: master module, fault sensing circuit, RF(receiver and transmitter), motor and LCD. The block diagram of the project is shown in figure 5. PIC16F877A is selected as microcontroller for the master module. PIC(Peripheral Interface Controller) as 8Kx14 Flash program memory, high performance RISC based CPU, low power consumption and it has up to 14 sources of interrupts. Fault sensing circuit used to find the defects and sends information to the respective systems through RF(Radio-Frequency). Motor drive is used to control the speed of the motor.



Fig 5. Block diagram of the project

C. Station Side

Station side block consists of RF Receiver(Rx) module, decoder, PIC microcontroller, LCD and buzzer.



Fig 6. Block diagram of Station side signal

PIC uses programmable serial port(USART), RF-Rx is used to receive the information transmitted by the train, it is then decoded and sent to the controller. The information is stored in RAM of PIC16F877A and displayed through LCD and buzzered at the right time.

D. System's Operating Principle

On-board equipment subsystem (figure 5) consists of control unit PIC16A877, fault sensing unit, LCD module, encoder and decoder, motor drive. The transmitted information is received through the RF to the driver's cabin, signal information which will direct the driver to operate the train, train's speed and location information is sent to the control center through the RF network. RF module is to provide complete transmission and reception information about the system. PIC16F877A has serial ports which communicates with the RF module, the TXD and RXD of PIC16F877A can directly connect the RXD and TXD of the other modules. Train running information is received from the RF, on one hand, it is send to the control center, on the other hand, which is stored in RAM of PIC16F877A, and is displayed through the LCD(16x2).

RF receiver module in control center subsystem receives the fault information, it is decoded to the controller. As a immediate move alerted by buzzer and display(LCD) at the right time.

III. PRINCIPLE OPERATION OF TRAIN CONTROL

The flow diagram(Figure 7) explains how the operation carried out in the system.

Depending upon the signal, the train will perform its action. If the signal is green train will be in moving condition else train as to be at halt. Checks for the location of the train and route, and added checks the faults instantly, reports and finds a solution for the fault. Each fault is separately diagnosed and checked. Once after the clearance, the train continues its action.

If the train goes in wrong direction, merge out, cracks on tracks, explosives, obstacles are identified and solutions will be provided instantly. Thereby, accidents and dangerous conditions would be reduced, safer travel is ensured.



Fig 7. Flow chart of train control operation

IV. SIMULATION RESULTS

Simulation results includes the entire techniques like automatic traffic signal control, detecting train track fault and safety protection. PIC microcontroller plays a vital role in executing the simulation.



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Fig 7. General simulation of intelligent train model (indicating the signal is in red, train is in halt).

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General simulation for Intelligent train model(figure 6), simulation is done using Proteus software, programmed with the MPLABX IDE and coding's are written in Embedded C. MPLABX IDE is a software program that runs on a PC (Windows, Mac OS, Linux) to develop applications for Microchip microcontrollers and digital signal controllers. It is called an Integrated Development Environment (IDE), because it provides a single integrated "environment" to develop code for embedded microcontrollers.

Proteus is software for microprocessor simulation, schematic capture, and printed circuit board (PCB) design. It is developed by Lab center Electronics. MPLABX does the work of compiling, debugging, Embedded C is used for programming. So the front end simulation is done by Proteus and rear end simulation is done by MPLABX with the help Embedded C coding.



Fig 8. Simulation result for Obstacle sensor

The IR Obstacle sensor is used to detect the faults, mainly designed for robust operation. Figure 8, shows the fault that is detected using the obstacle sensor. Fire sensors senses the fire as a signal and pass the information to the nearest railway station and added a buzzer is placed to alert the passengers, also alert the driver to make the train come to halt. In figure 9, shows the result of fire sensing module.



Fig 9. Simulation result of Fire sensor

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Metal detectors have become a common staple in recent days. There are three different metal detector technologies, each one serves its own purpose to each type. Metal detectors can be used in security fields, military, industrial settings. Here in this project, proximity sensors are used as a meatl detector.



Fig 10. Simulation result of Metal detection

In the above figure 10, fault is detected using metal sensing.

Proximity sensor is used for the high reliability and long functional life. It is able to detect the presence of nearby objects without any physical contact and some sensors have variation of the nominal range or means to report a graduated detection distance. LCD(16x2) used to display the information to driver's cabin and to the control room.

IV. SIMULATION RESULT FOR COMMUNICATION BETWEEN THE SERVER AND THE DRIVER'S CABIN

In an additional aspect, tried implementing the communication part in Network Simulator-2(NS2), it sends the information about the wheel alignment and wagon position to the server and the engine driver which helps to avoid accidents and added the caution message will be sent to every individual wagon in order to safeguard the passenger's lives. The below simulation shows the initial point, figure 11.





The sender sends ACK to the receiver, to check for the free path. Once getting the confirmation from the receiver, sender starts sending the data. In figure 12, sender sends the information to the server. This communication is done, so that main unit, driver and passenger will be on alert everytime.



Fig 12. Sending data to the server

Finally, data will be received to the server and that data would be send to the main unit by the server. Figure 13, shows the data is sent to the main unit from the server.



Fig 13. Server sending data to the main unit

Above simulation helps to communicate the entire status of the train like position of the wagon, location and if any issues arise that would be communicated to the other wagons, control room(main unit) and to the driver's cabin. This would avoid accidents and helps to provide safe journey.

V. CONCLUSION

In a demanding society, by using advanced techniques, railway network can be brought under a single cloud radar system which efficiently make passengers journey comfort. In this paper, considering the traffic conditions various parameters are introduced for the betterment of safety and added it shows improved adaptability to weather conditions, maintainability of centralized(cracks) and simplified equipment design. Sensors like IR, Proximity and fire sensors are used to detect the faults(obstacle, metal, fire). In real time, Ultra Sonic crack detection can be used to detect the cracks on tracks, this technique provides accurate and highly efficient results. GPRS can be used instead of RFID, it provides with no distance restrictions and high reliability. The authors hope that their idea can be implemented in large scale in the long run to facilitate better safety and secured travel.

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